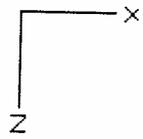
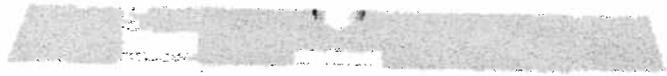
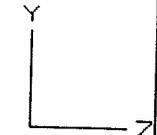
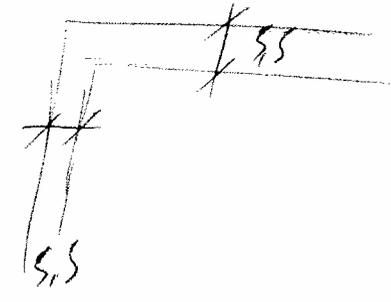
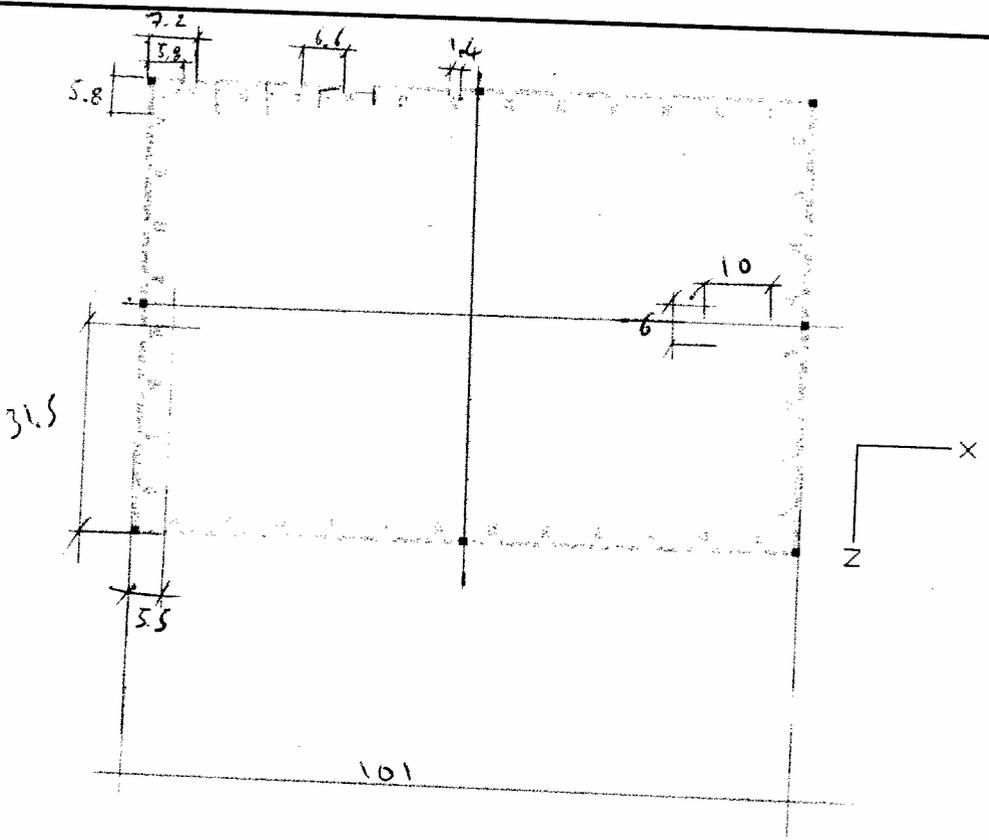
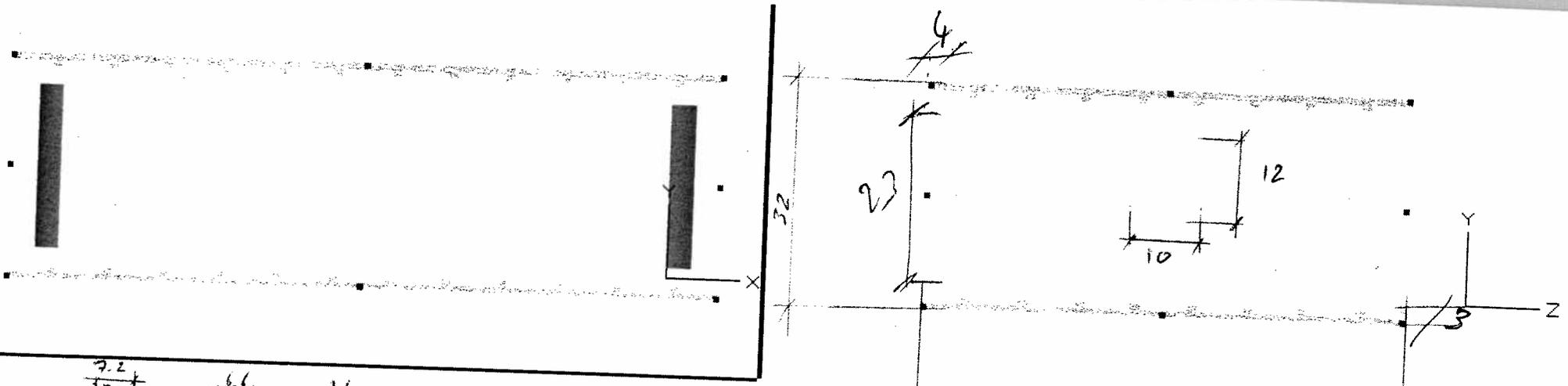


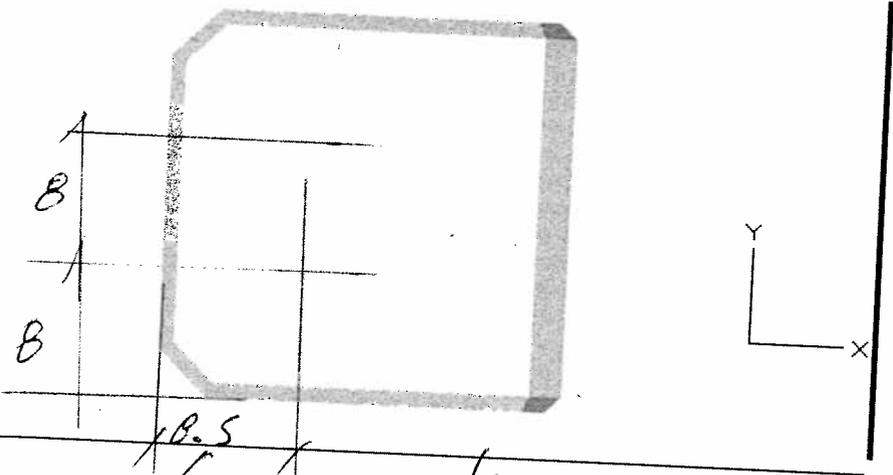
64 mm

58 mm

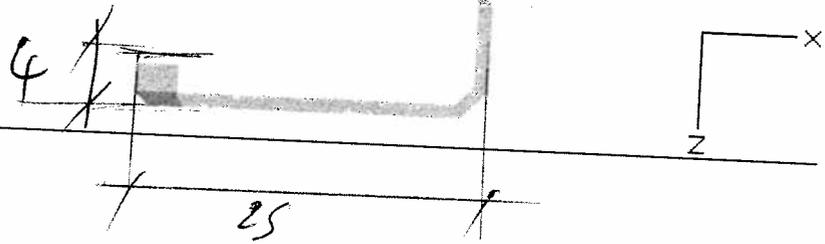
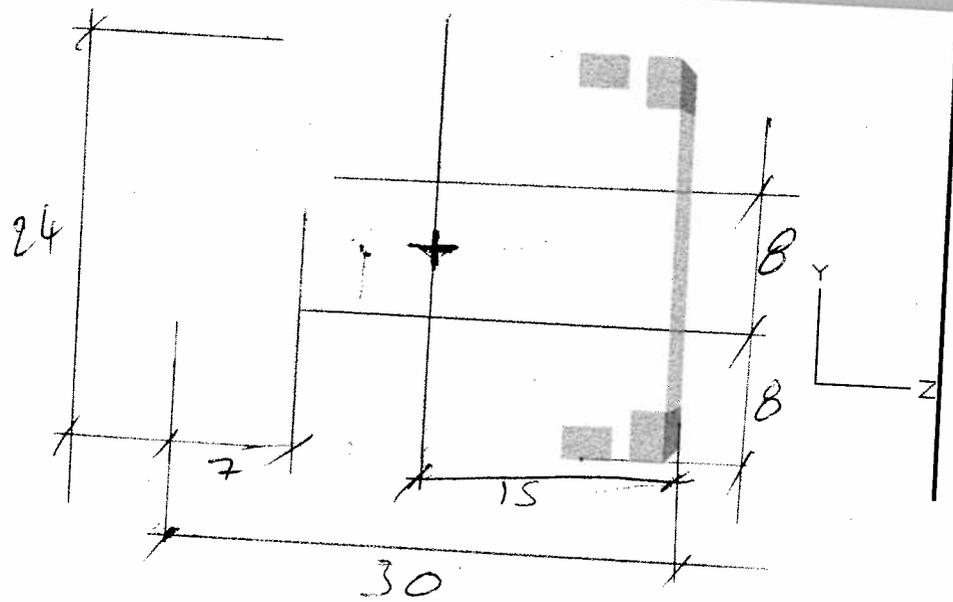




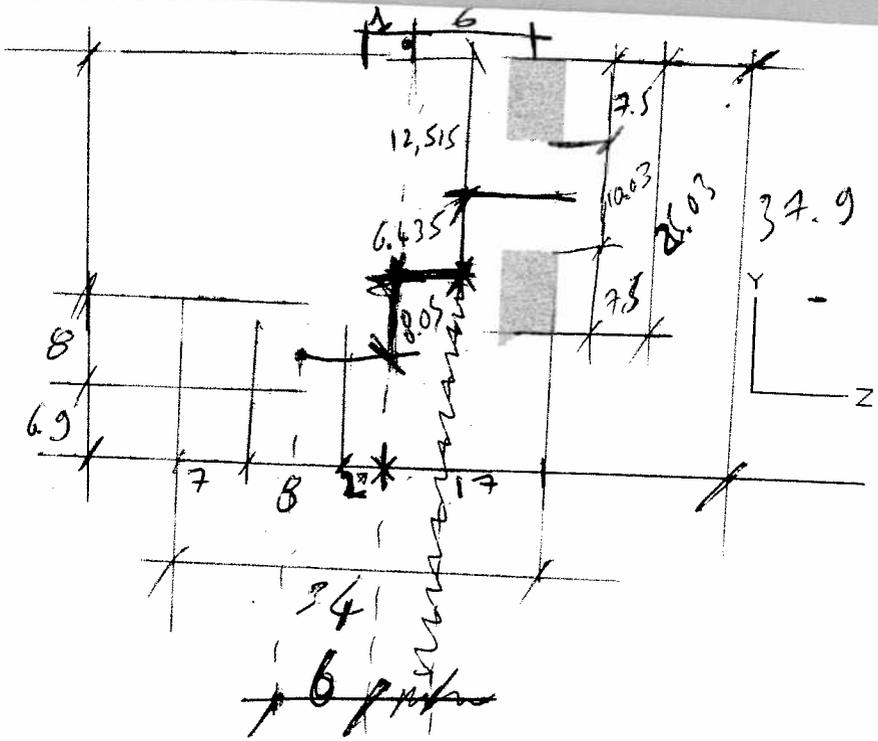
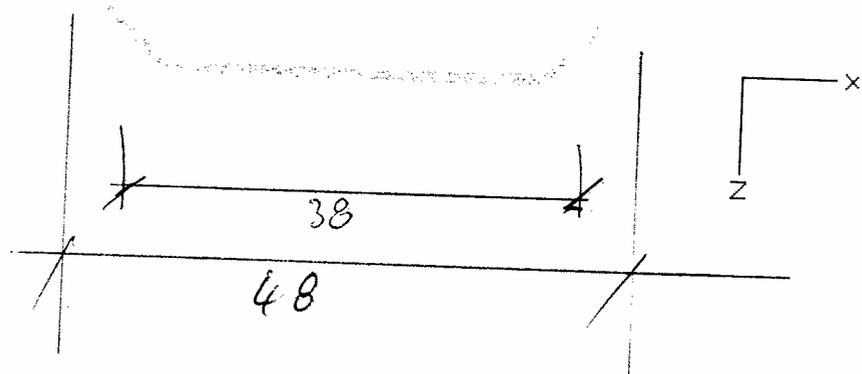
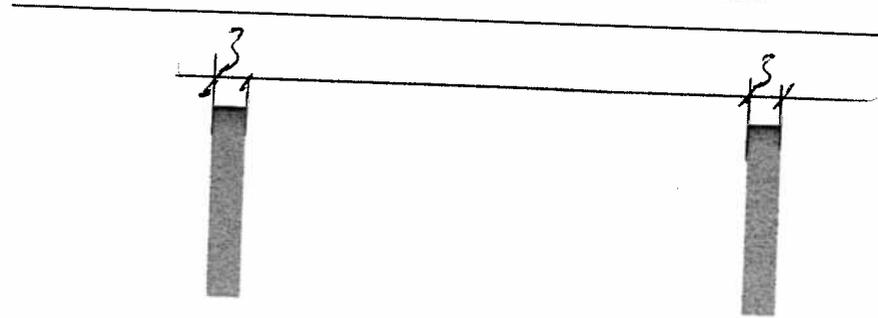
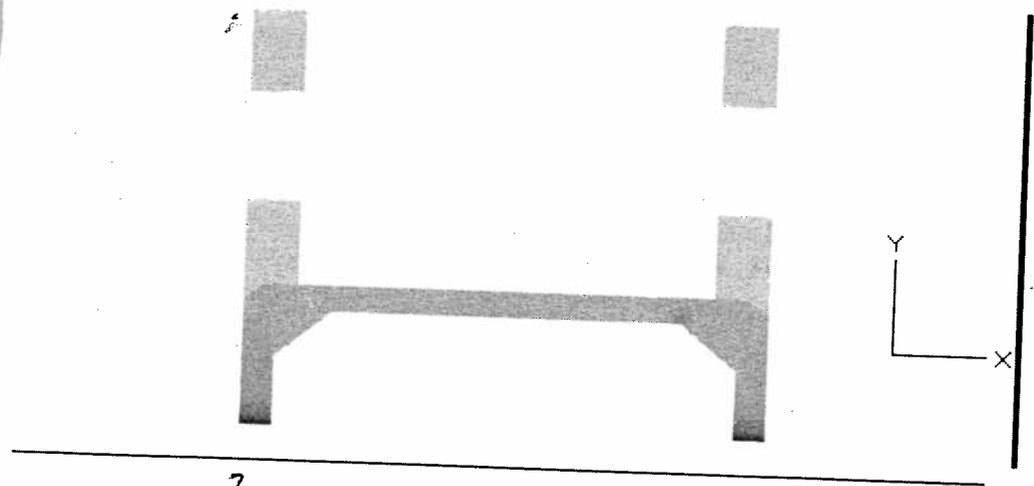
368 mm



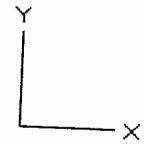
should be B



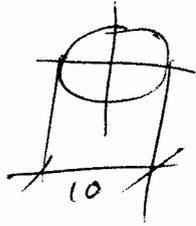
\triangle 24 on the real result



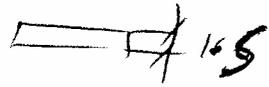
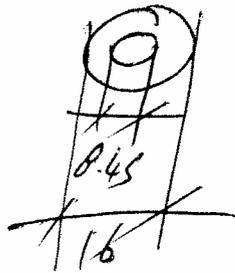
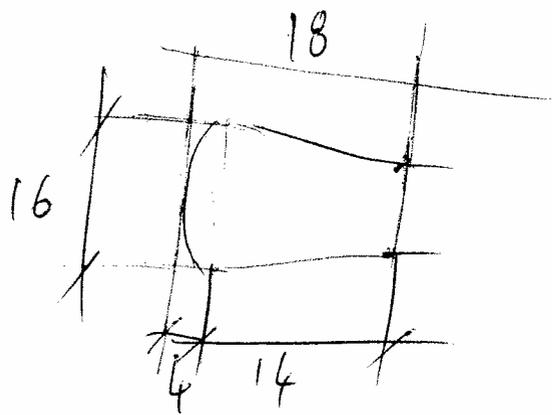
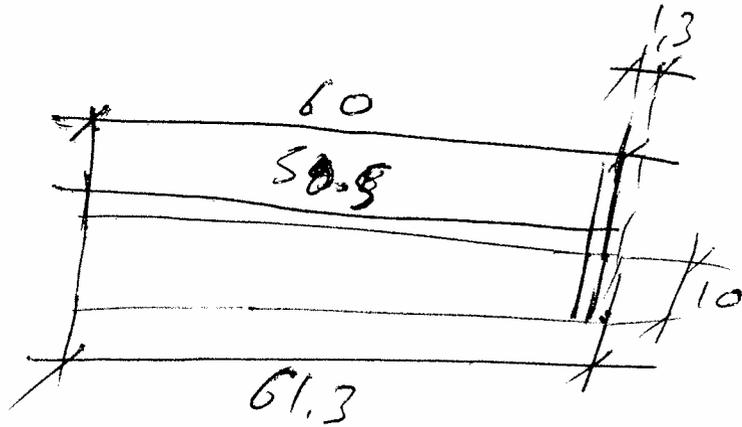
CON Z + 6mm

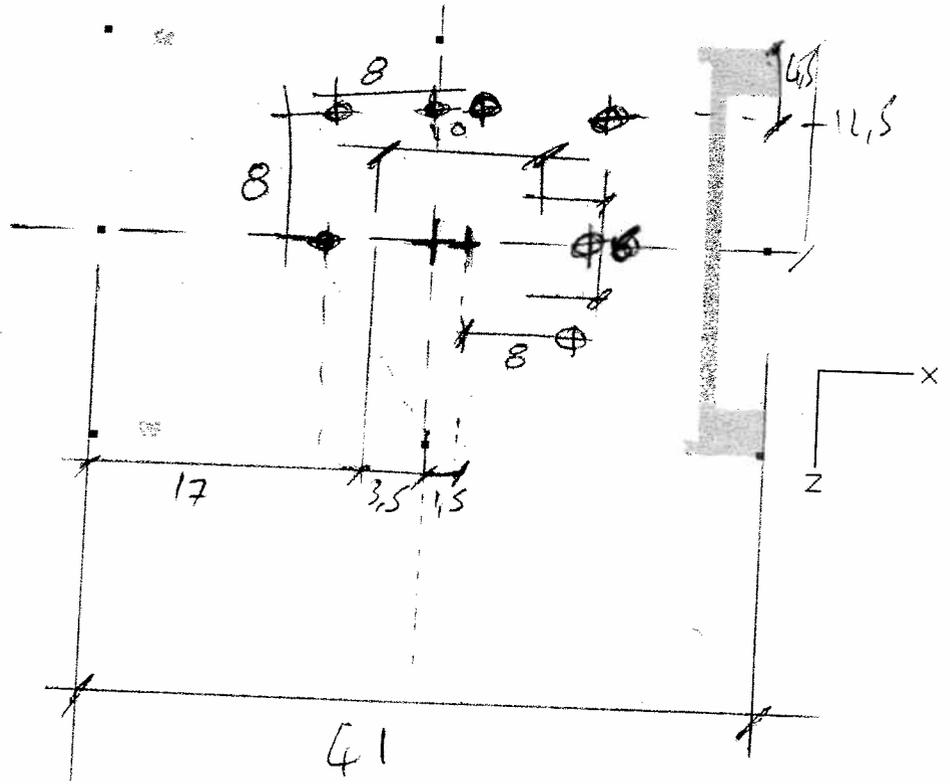
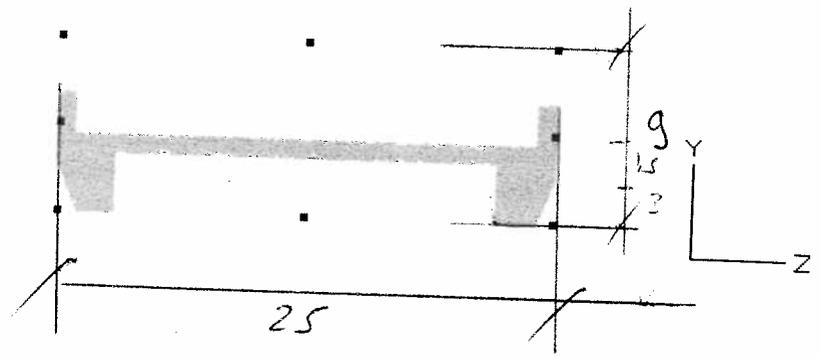
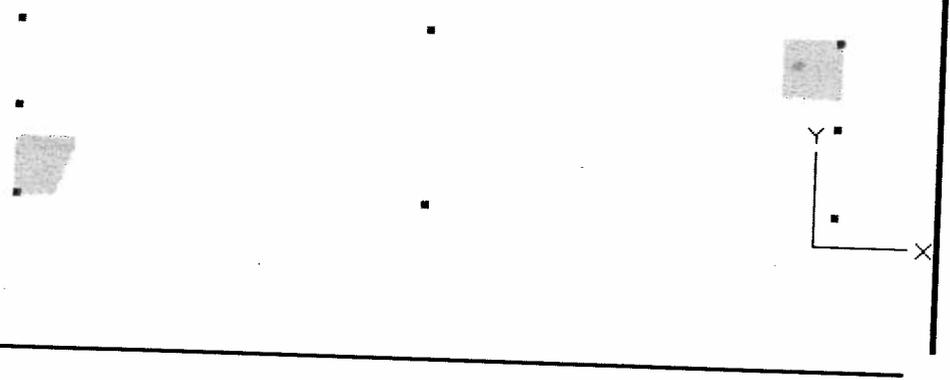


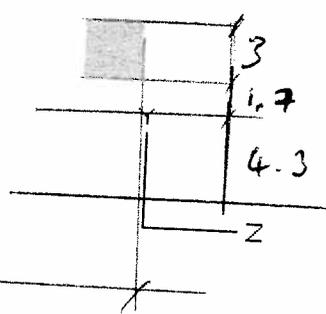
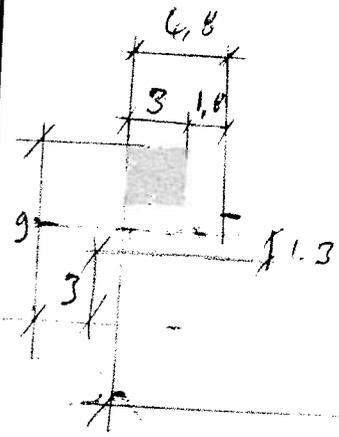
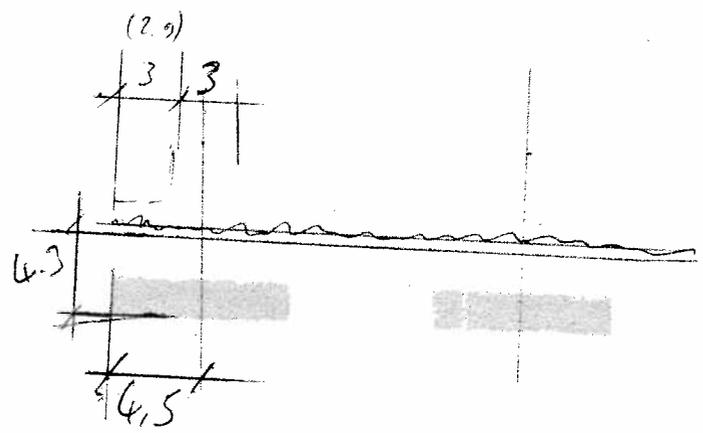
LEG EXTREMITY



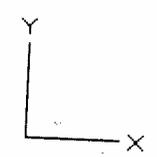
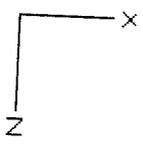
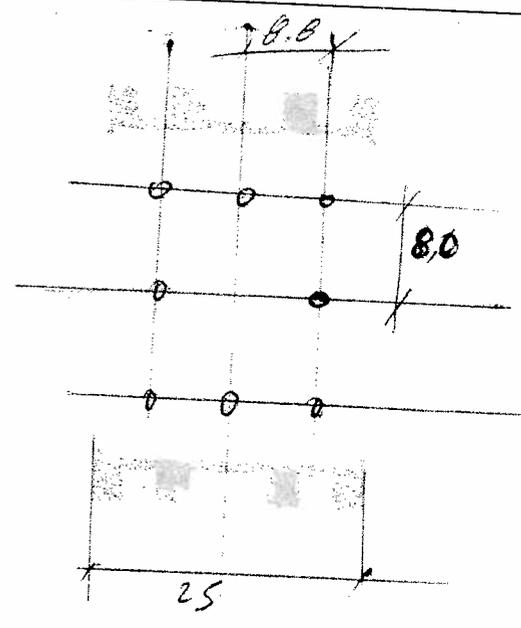
$$\begin{array}{r}
 7.5 \times 18.5 \\
 26 \\
 \times 10 \\
 \hline
 65
 \end{array}$$

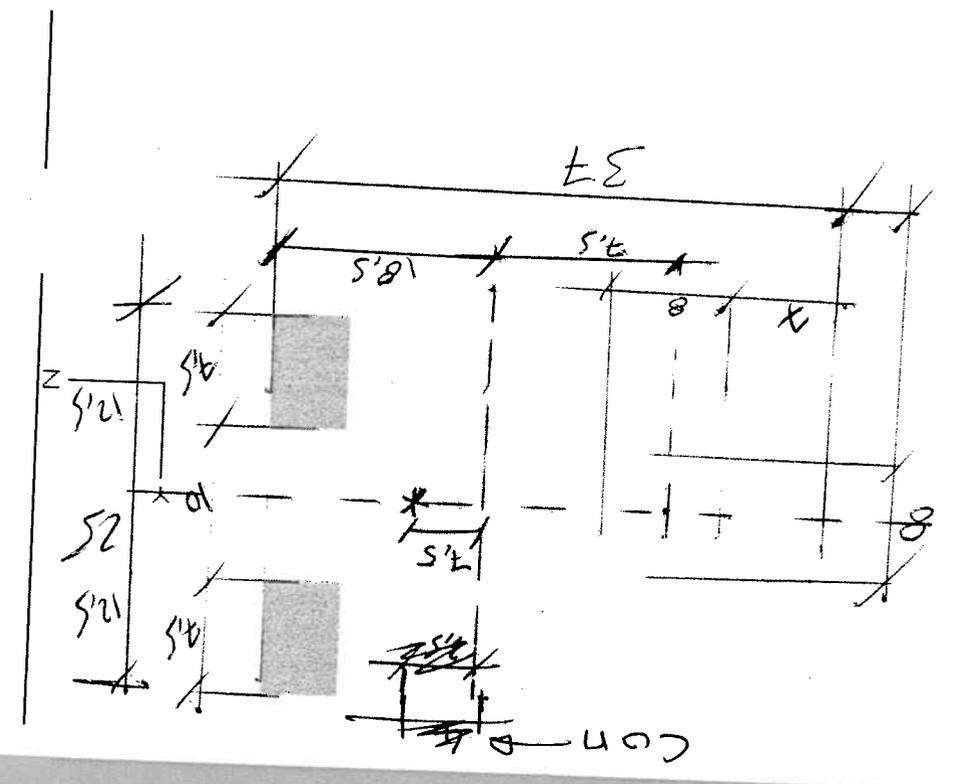
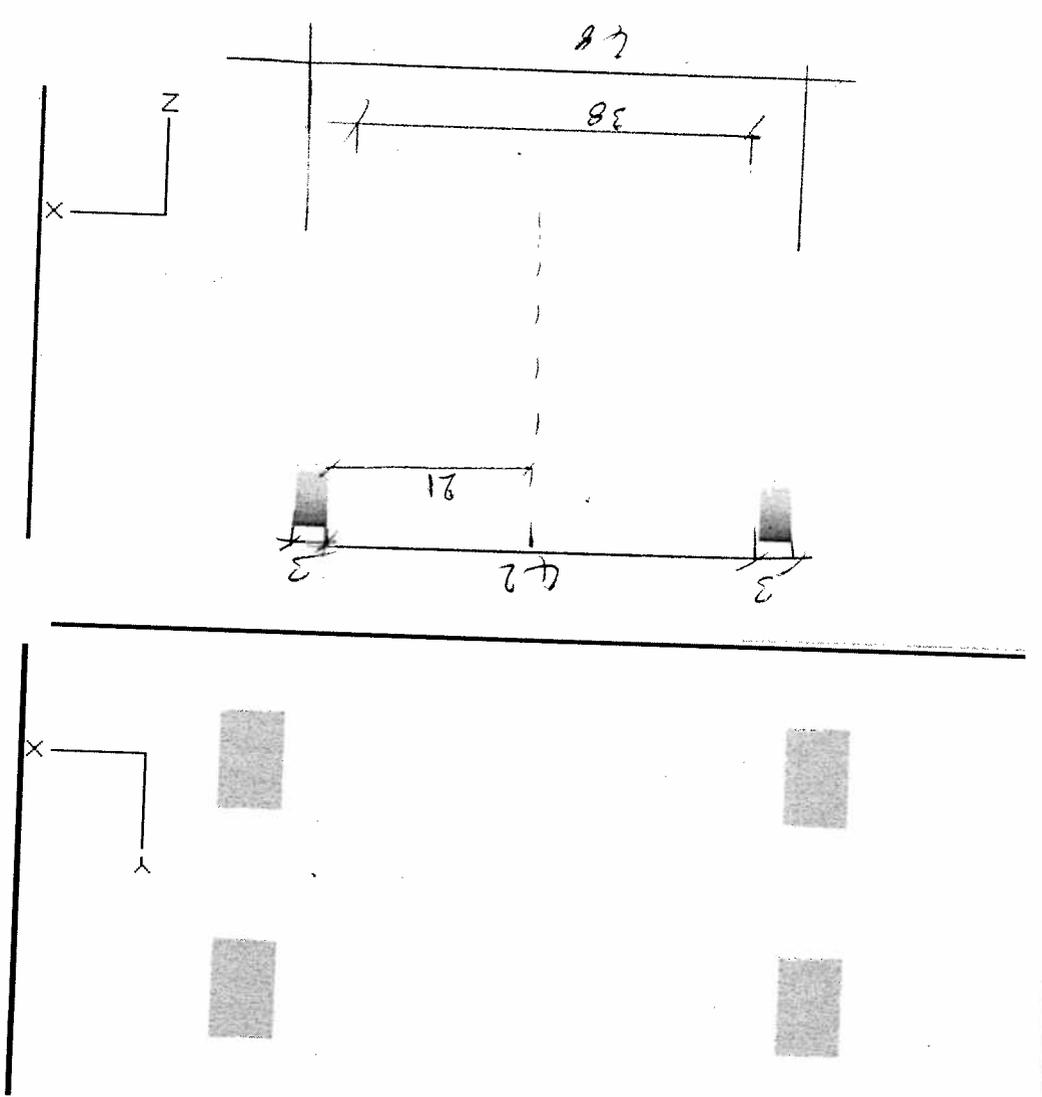
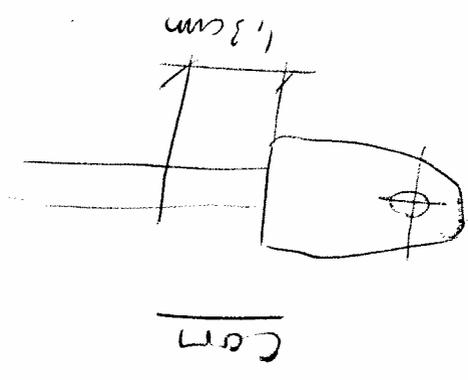




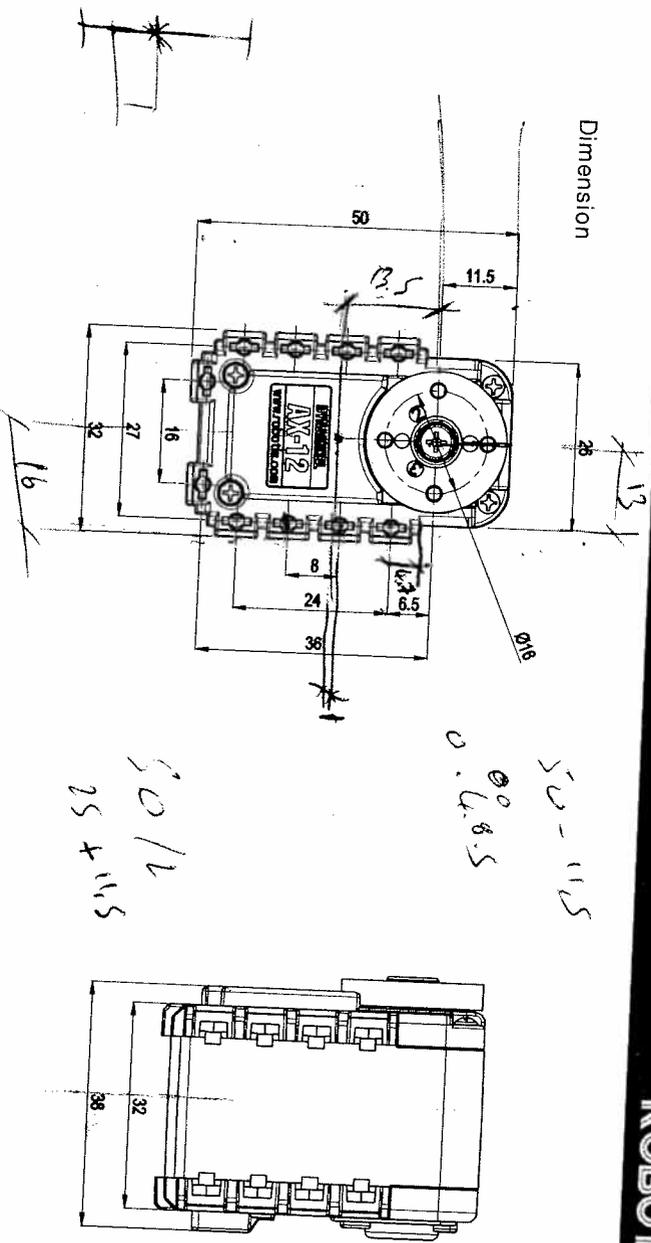


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DYNAMIXEL AX-12 ROBOTIS



CM-5
 Dedicated AX-12 control box. Able to control 30 AX-12 actuators.
 6 push buttons (5 for selection, 1 for reset)
 Optional installable wireless devices available
 Battery compartment (AA x 8) with recharging capability (when connected to an external SMPS)

