Loïc Matthey	Semester Project Planning 3.10.2007													
Week	18.9-21-9 <b>1</b>	24.9-28.9 <b>c</b>	1.10-5.10 <b>s</b>	8.10-12.10 <b>4</b>	15.10-19.10 <b>c</b>	22.10-26.10 9	29.10-2.11 <b>2</b>	5.11-9.11 8	12.11-16.11 <b>6</b>	19.11-23.11 <b>D</b>	26.11-30.11 1	3.12-7.12 <b>12</b>	10.12-14.12 <b>13</b>	14 21.15-51.11 <b>14</b>
Task	1	5	1	Θ.	15.	22	76	5	12	19	26	(r)	10.	17.
Literature review														
Theory review														
Definition of problem and goals														
Construct oscillatory element														
Study element alone														
Study coupling of elements														
Study feedback theoritically														
Construct steady-state movement as reference point														
Construct chaotic movement														
Study feedback for the experiment														
Design benchmark														
Benchmark chaotic controller versus a random controller														
Study of applicability on robotics														
Use the chaotic for steady-state movement (if time available)														
Middle report and presentation														
Final report														
Milestones		Theory element  Theory coupled elements												
	Steady-state movement Middle Report													
							•	Cha	otic move	ement	Ben	chmark		
													Final I	Repor